

Multi Objective Optimisation of an aeronautical vaporizer by coupling of Genetic Algorithms and CFD techniques

**L. Bucchieri - Engin Soft
M. Galbiati - Engin Soft
P. DiMartino - Fiatavio**





-  **EST - Fiatavio Research Programme**
-  **Optimisation concepts and strategy**
 -  DOE, MOGA, RSM, ANN
-  **Basic CFD problem, design and logic setup**
 -  Vaporiser initial run
 -  Parametrisation
 -  Design setup and logic
-  **DOE and MOGA screening**
 -  SOBOL screening
 -  MOGA high mutation generations
-  **MOGA and RSM optimisation**
 -  Response surface fitting
 -  MOGA and RSM blending Runs
-  **MCDM final design**



Partners: Engin Soft Trading CAE company, FIATAVIO aerospace, University of Trieste






Develop a programme to link CFD techniques and optimisation techniques.

-  needing the exploration of a **wide range of variability** for the design parameters
-  **involving several aspects** (MULTIDISCIPLINARY)
-  with **several**, may be conflicting, **objectives** (MULTIOBJECTIVE)
-  **respecting the “computation budget”** available for problems involving high CPU demands ie. 3D RANS CFD



Develop parametric test models:

-  gas turbine rotor blade
-  shroud sealing flows
-  fuel vaporiser (Fiatavio supplies a typical vaporiser design to be optimised within the framework of technological innovation of the combustor product)



Optimisation techniques can roughly be divided in three classes



screening techniques: DOE (Design Of Experiment) methods which are intelligent ways to minimize the experiments getting the maximum of information out of them



Gradient or Genetic Algorithm techniques to:



find the optimal solution on a N-dimensional surface with gradient methods



find the optimal solution after N-generations of genetically selected experiments
























Interpolating techniques



Finding optimal solution without running CFD analysis, but on an interpolating surface of previously run solutions: RSM (Response Surface Method)














Finding optimal solution without running CFD analysis, but on an interpolating neural network of transfer functions between input parameters and output objectives: ANN (Artificial Neural Networks)

-  **ALL platforms are supported**
 -  Browser based technology
 -  JAVA,CORBA,XML)
-  **Capability of handling any computing services**
 -  files or API (Application Protocol Interface) ...
 -  from CFD to MS-EXCEL
-  **Optimisation Algorithms**
 -  Multi-Objective Genetic Algorithm,
 -  Simplex
 -  Gradient based methods
 -  DOE (Design of Experiments)
 -  RSM
 -  ANN
-  **Decision Support tools**
 -  Pareto Filters
 -  MCDM
 -  Statistical charts
 -  Parallel charts
-  **The order of magnitude is:**
 -  100 analysis automatic analysis for typically 20 variables, 3 objectives, 3 constraints
-  **FRONTIER allows the user to extract the maximum of information allowed by the user-defined CPU budget**






Set up in CFX4.3:




-  **geometry 3d in cylindrical coordinates**
-  **fully compressible model**
-  **mass fraction 1 for vaporised fuel**
-  **mass fraction 2 for recirculating products from combustor can**
-  **lagrangian tracking for particle phase**
-  **spray model employed with turbulent dispersion**
-  **Reynolds Stress Model for turbulence**
-  **Two numeric procedure to guarantee convergence**
 -  **15 X 100 it with k-epsilon**
 -  **15 X 100 it with RSM but restart from K-epsilon**
-  **100 maximum down to 50 minimum fluid iterations for each particle coupling, dynamically set by USRCVG**

Boundary conditions




Inlet 1

-  **T = 900 Kelvin**
-  **Air mass flow = 40% total**
-  **Swirl angle = 40 degrees**

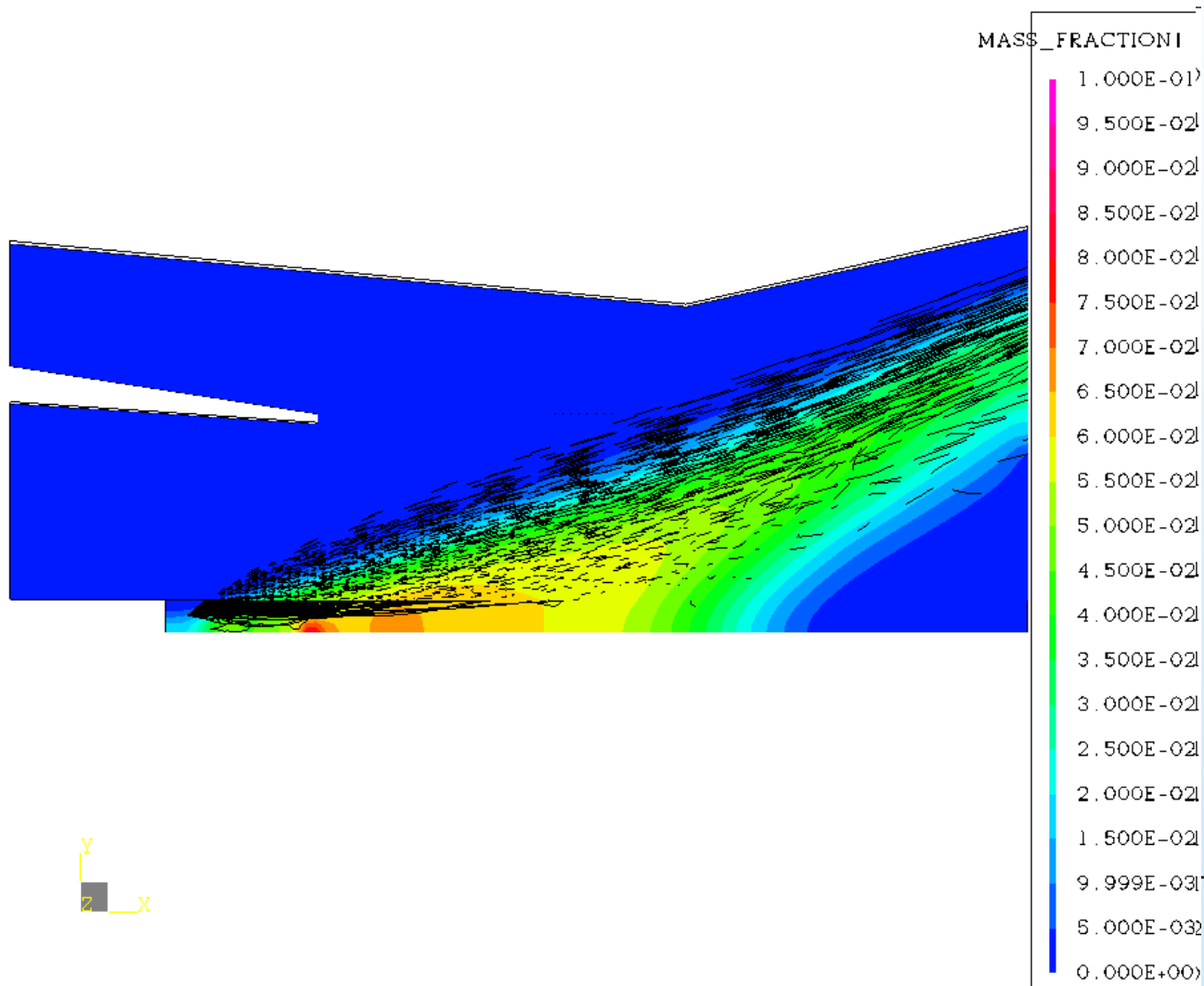
Inlet 2

-  **T = 900 Kelvin**
-  **Air mass flow = 60% total**
-  **Swirl angle = 40 degrees**

Atomiser (fuel droplet inlet)




-  **SMD 45 microns**
-  **Rosin Rammler exponent 3.0**
-  **Fuel/Air mass flow ratio = 5.0%**





CFX








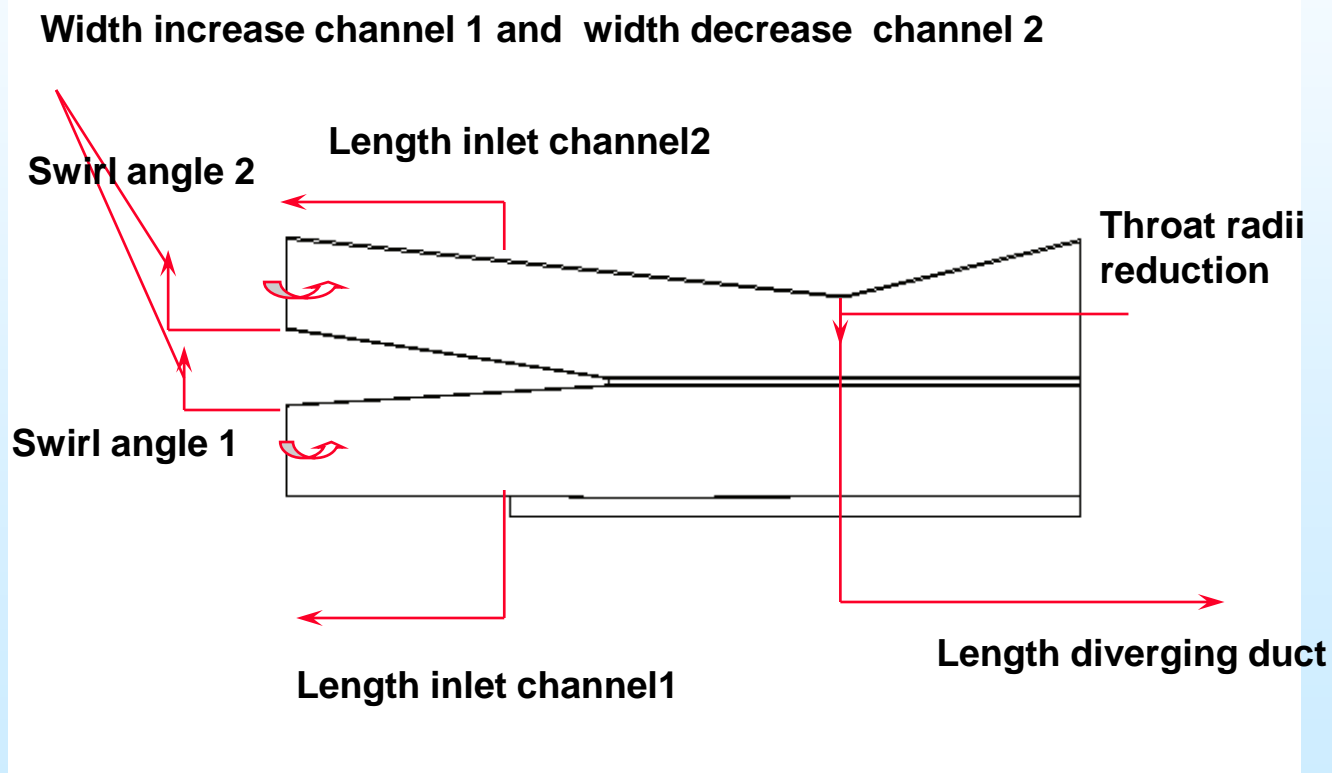
The basic fuel vaporiser must be improved:

-  **inlet air and fuel mass flow are given**
-  **inlet swirl angles and air mass ratios are free**
-  **dimensions are limited**

-  **pressure drop must be minimised**
-  **recirculation must minimised**
-  **fuel vaporisation must be maximised**
-  **length must be minimised**

-  **recirculating combustion products must not go upstream the throat**
-  **swirl number at exit is set to combustor requirements $Sw_{no}=0.50$**
-  **convergence must be obtained**

Design Problem



Input parameters

	Definition	Original	Minimum	Maximum
L1	Length channel 1	7.0	2.0	15.0
L2	Lengtht channel 2	7.0	2.0	15.0
B1=-B2	Increase Width channel 1 = decrease width cahnnel 2	0.0	0.0	5.0
Delta R1	Throat radius reduction	0.0	0.0	3.0
Length	Length diverging duct	15	10	30
Alfa1	Swirl angle channel 1	40.0	10	80
Alfa2	Swirl angle channel 2	40.0	10	80

Note: b1 and b2 change the area hence the mass flow rate ratios from the pressure plenum

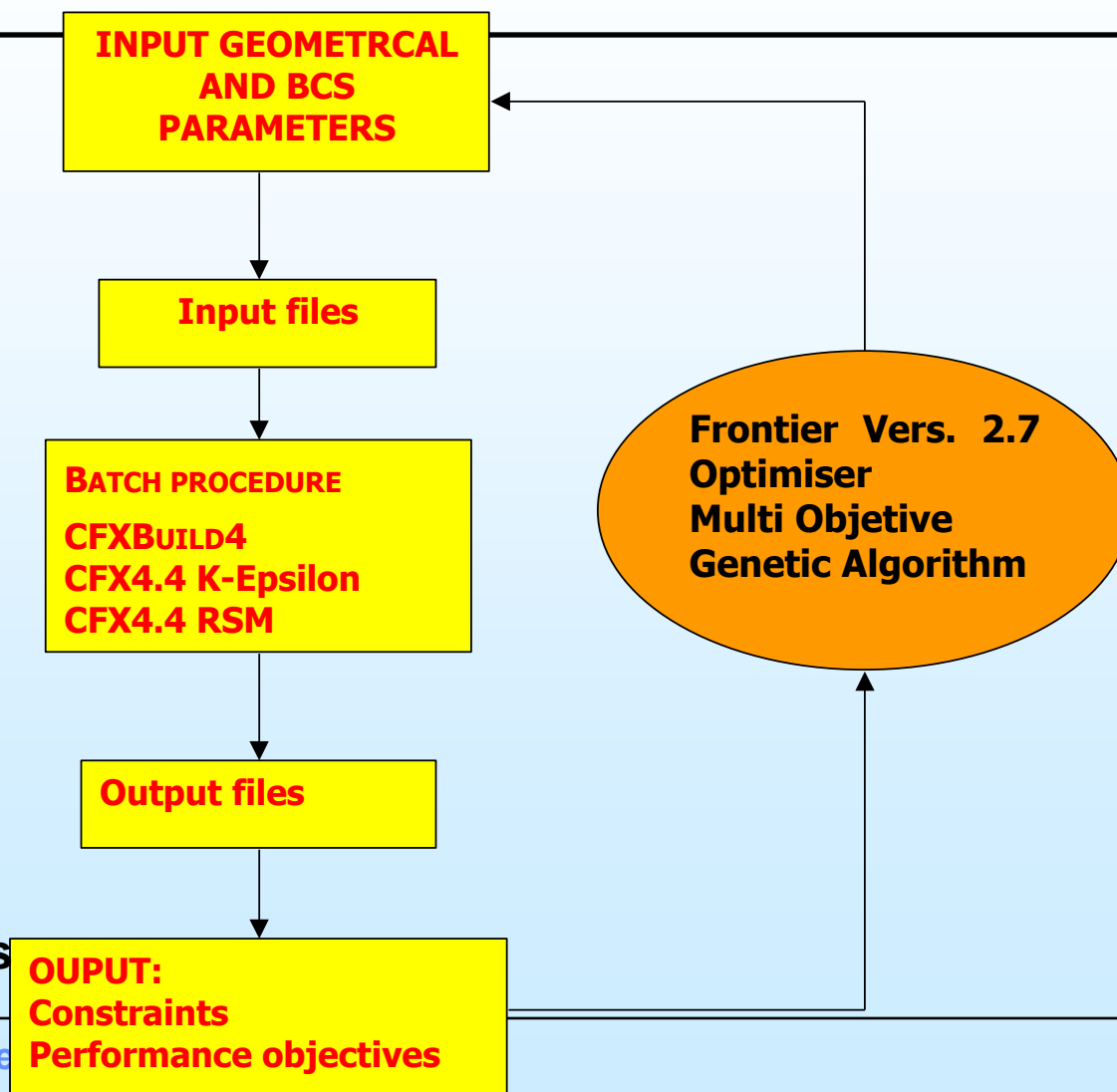
Logic Setup in Frontier2.7
Parametric input

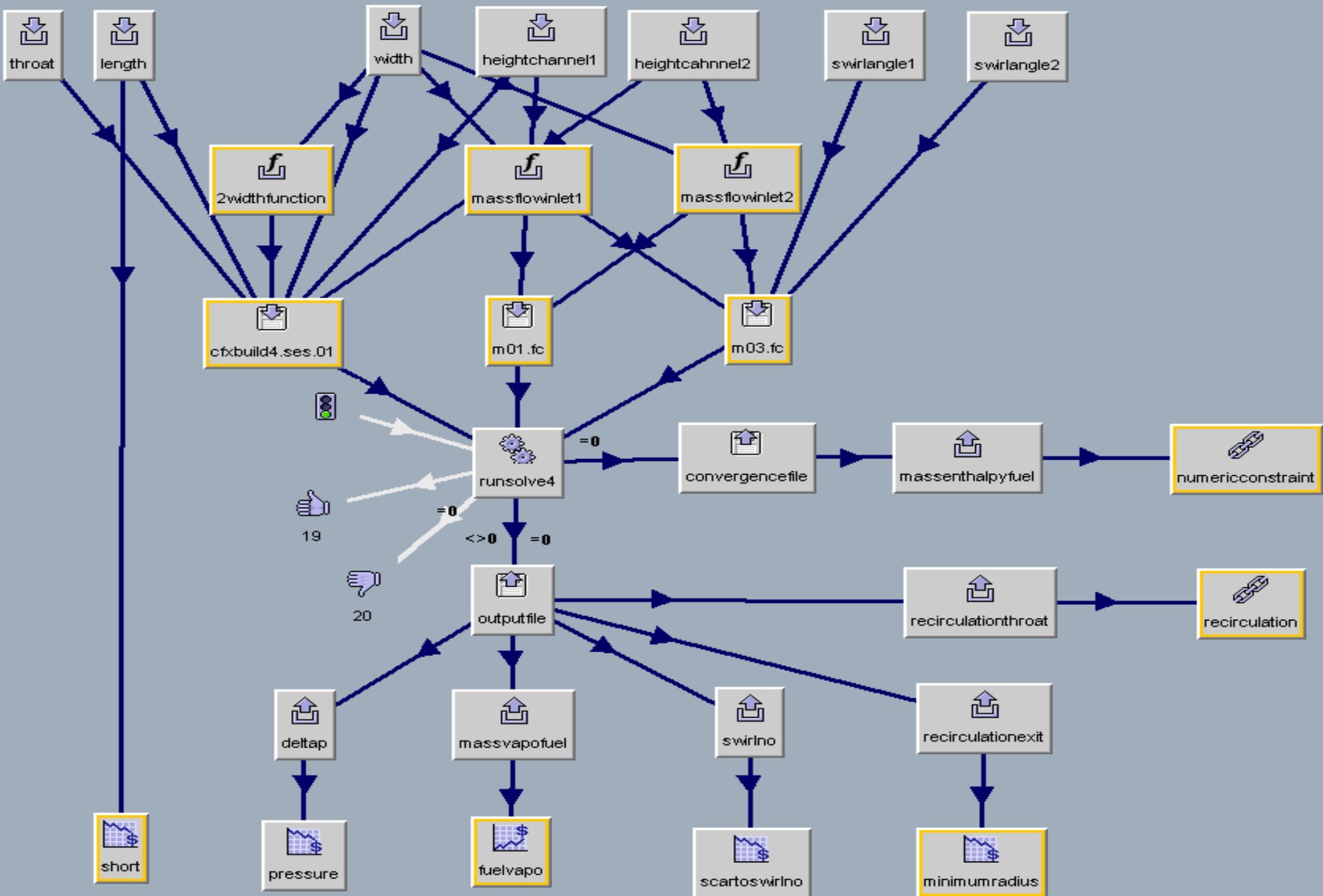
File input handling

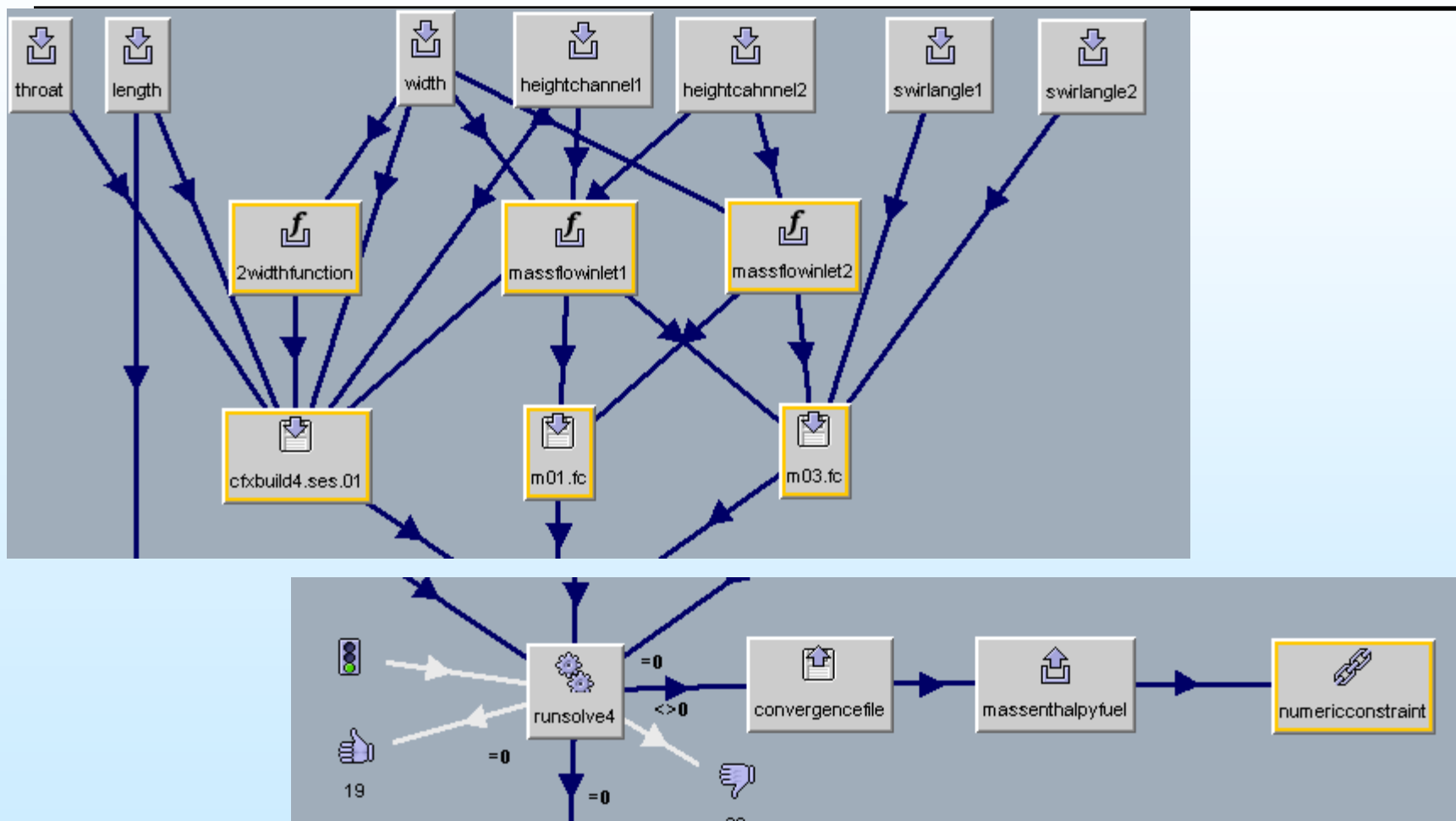
Batch procedure

File output handling

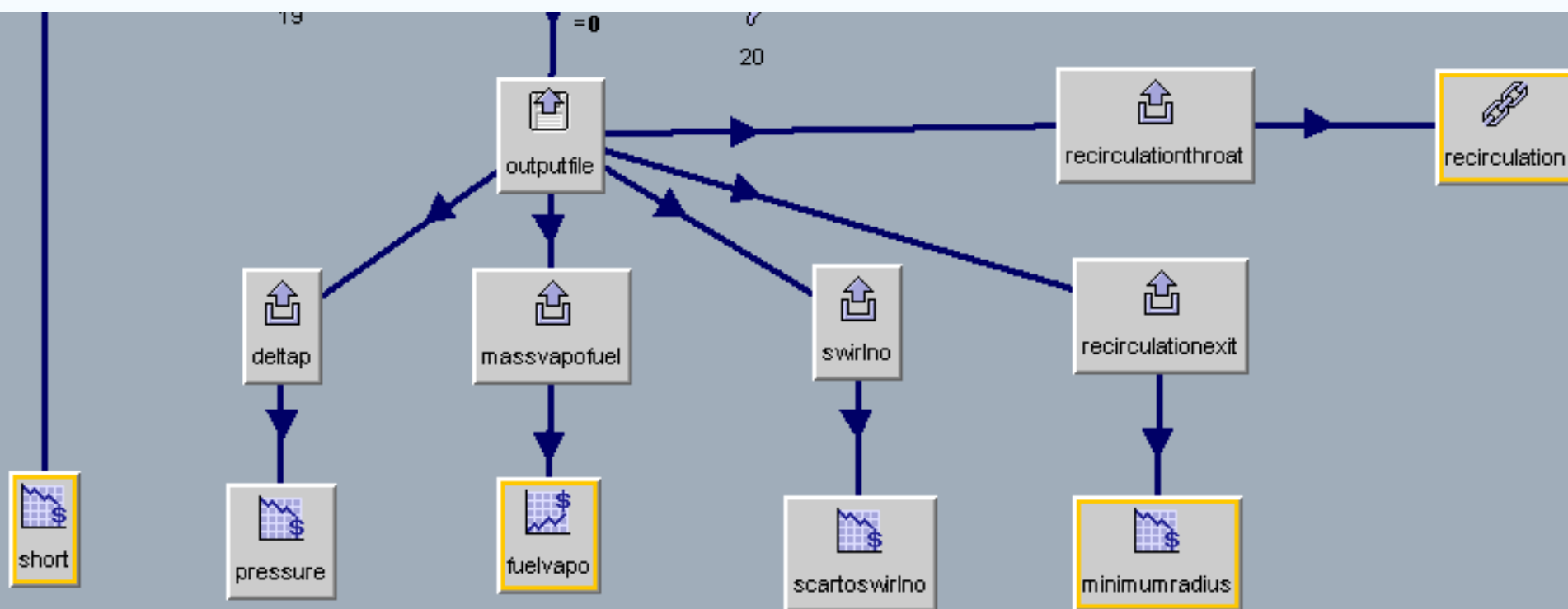
Output feedback-parameters







```
# ! /bin/sh
cp /users/engin/FRON/inizio_copiami.db ./inizio.db
cp /users/engin/FRON/m01.f .
runbuild4 -b -sfp cfxbuild4.ses.01
mv *geo* m01.geo
runmi -cylaxis -fe m01.geo
rm m01.geo inizio.db*
mv *geo* m01.geo
rm setting* volm* cfxbuild4.ses.02
runsolve4 -f m01.f -c m01.fc -g m01.geo -enviro 01
runsolve4 -f m01.f -c m03.fc -g m01.geo -r m01.dmp -enviro 03
cp ./m03.dir/param .
cp ./m03.dir/CONVERGENZA .
rm -r m01.dir m03.dir m01.fo *.trk m01.dmp *.log file*
compress *.*
```





DOE



with 7 input parameters running a 3 level full factorial DOE (min, med, Max) would mean $3^7=2187$ experiments!!!! Or CFD analysis!!!



DOE reduction methods



Box-Benhkem



Taguchi



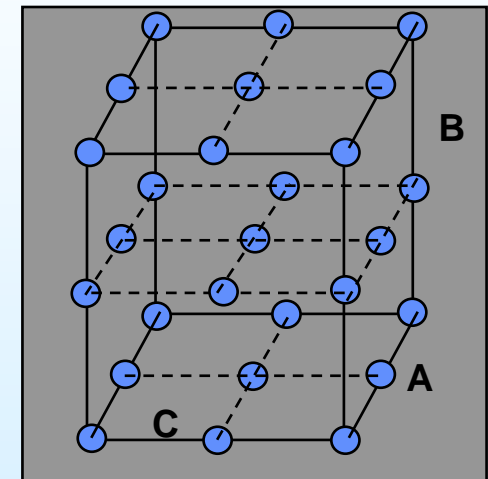
MonteCarlo



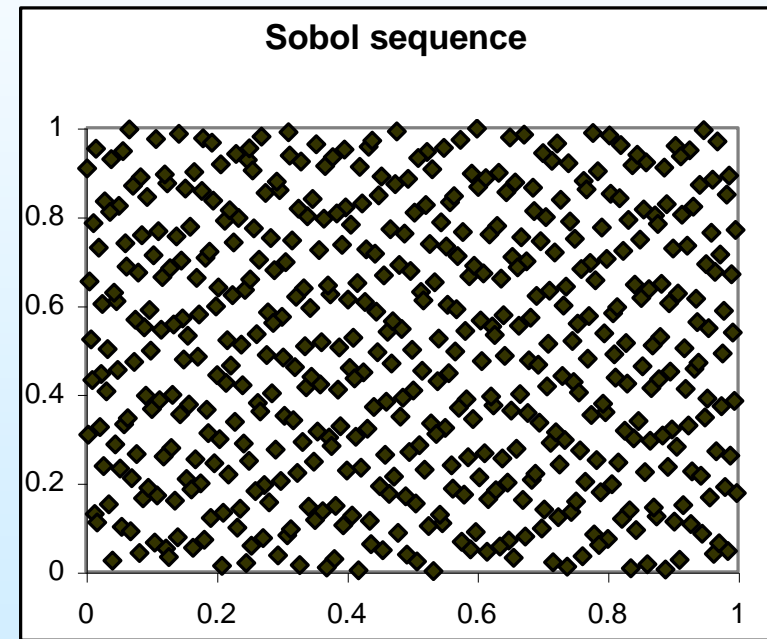
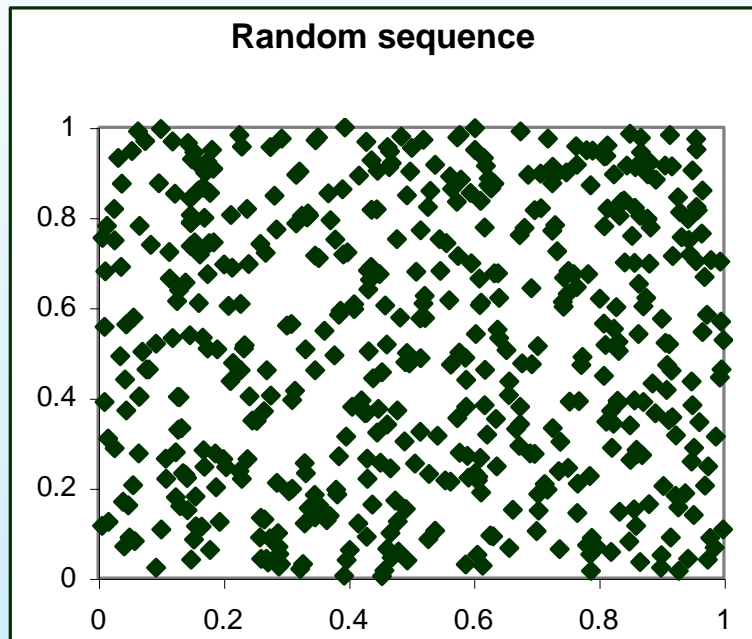
Random



SOBOL (a uniform Random)



Initial Screening





SOBOL

- ☞ In a 7 input parametric space with 5 objectives, needs 40-50 experiments for just a basic screening



MOGA

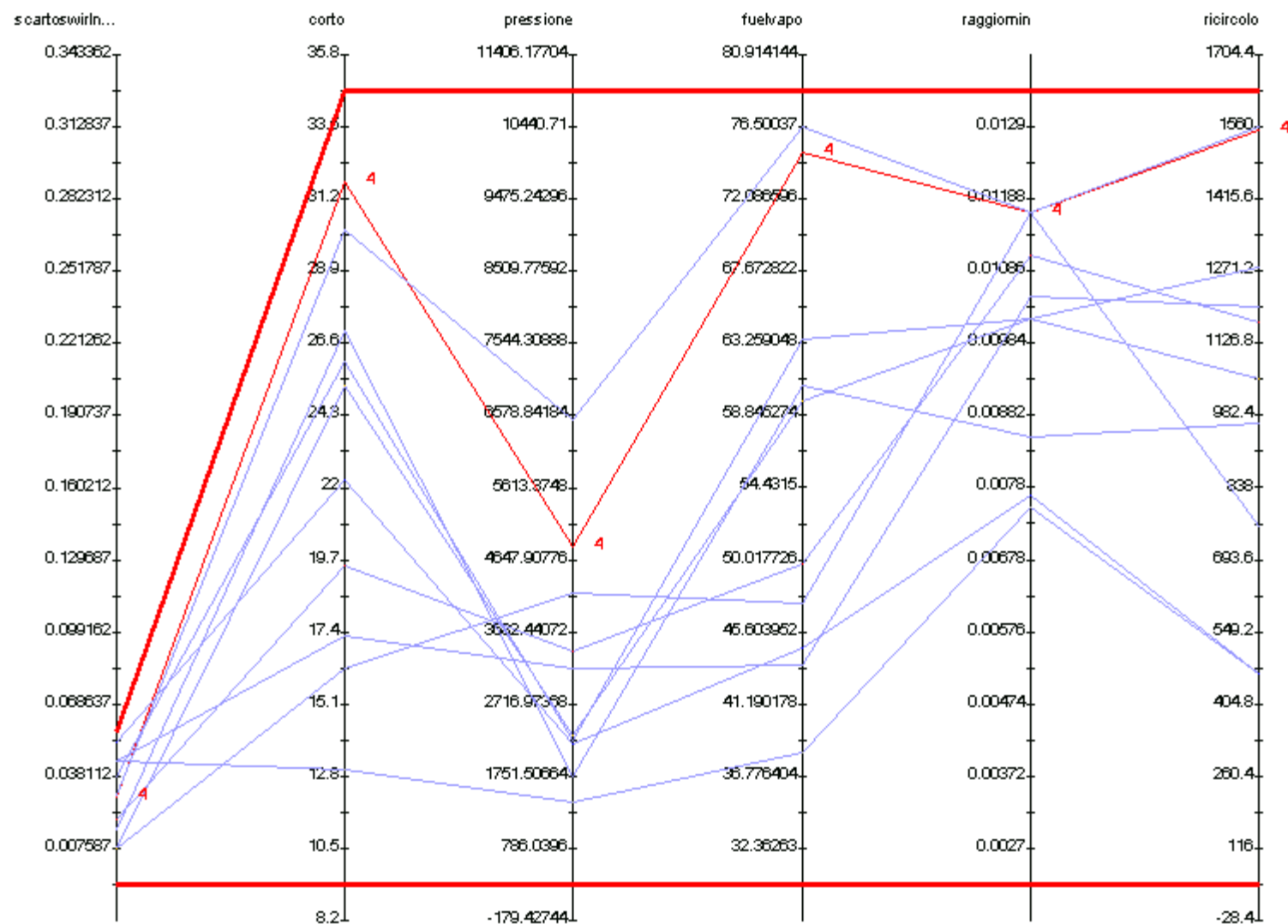
- ☞ Multi Objective Genetic Algorithm searches for optimal solution after N-generations of genetically selected individuals by:
 - ☞ selection
 - ☞ cross-over
 - ☞ mutation



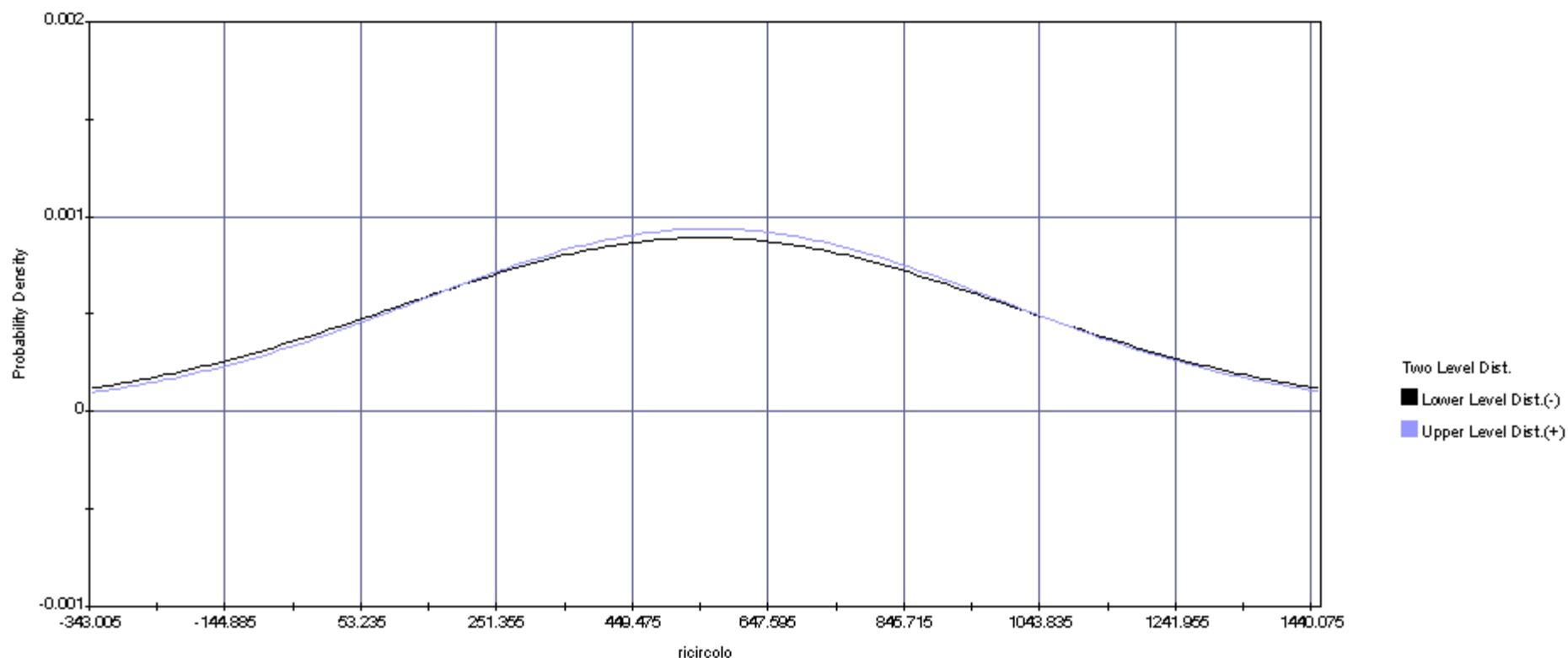
SOBOL and MOGA

- ☞ A first generation of 20 experiments (CFD analysis) is produced “randomly” in a SOBOL sequence
- ☞ MOGA runs 3 generation with high (respect to standard) mutation coefficient: 30%, hence 6 out of 20 experiments mutate each generation
- ☞ Total of 80 experiments are run: 20 are screening randomly, the other 60 evolve toward the optimal solutions with a mutation for 18 experiments

Initial Screening



Two Level Effect for Variable - h2



Level Moments

n-	39	n+	33
mean-	5.555E2	mean+	5.620E2
std.dev-	4.47E2	std.dev+	4.249E2

Student Parameters

delta	6.569E0	mean std.dev.	1.034E2
t-Stat.	6.355E-2	significance	5.129E-2



Parameter reduction

- ☞ The length of the inlet channels are fixed, since they do not heavily influence the output.
- ☞ Pressure loss is not considered an objective, since the pressure requirements can always be satisfied.
- ☞ The length parameter is extended to 50 mm
- ☞ Swirl number deviation is changed into a constraint
- ☞ 2 input parameters and 1 objective are eliminated
- ☞ Logic is reduced



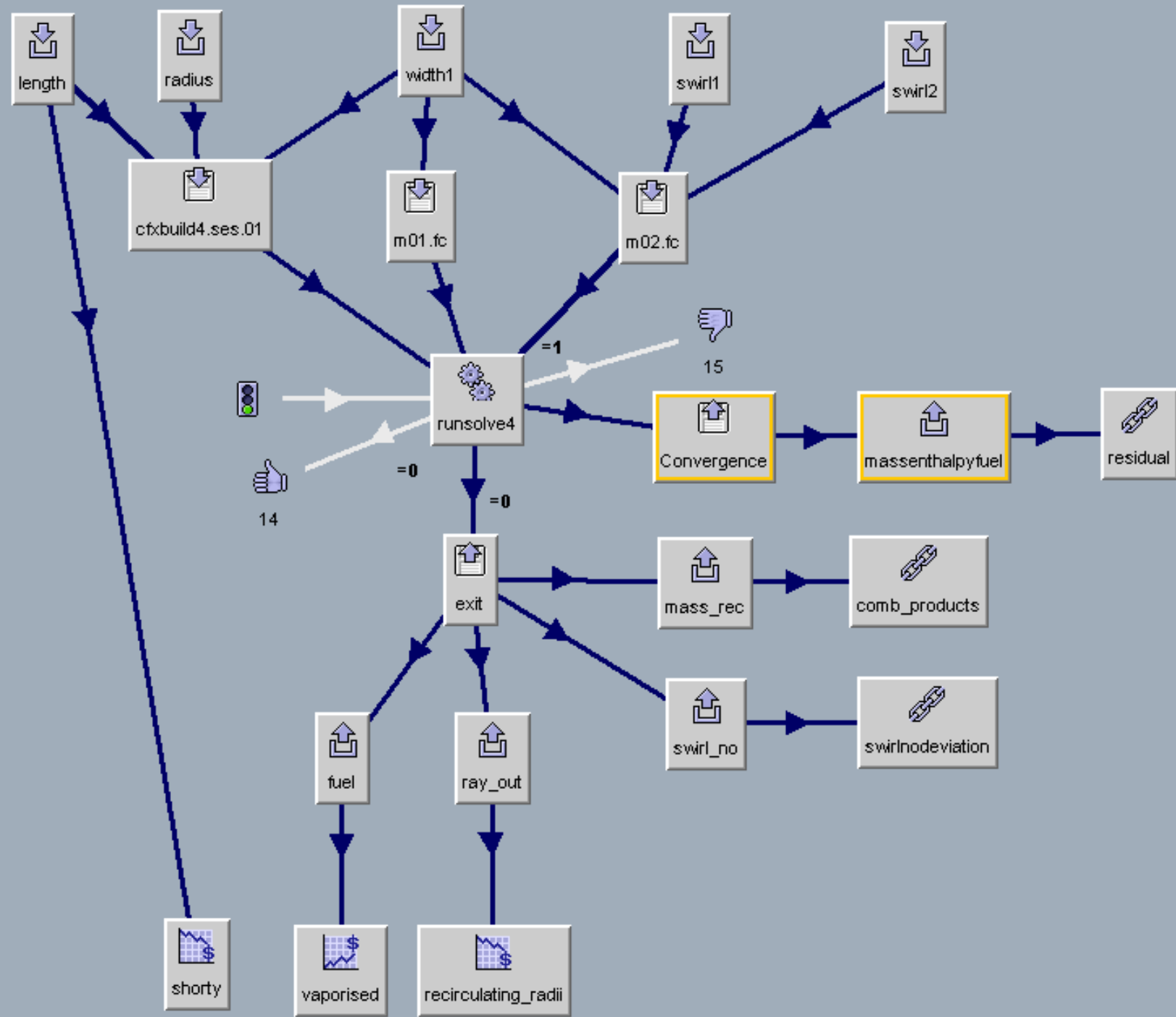
RSM

- ☞ Response surface is fitted and trained to reduce CPU time



Multi Criteria Decision Method - post-processing

- ☞ MCDM functions are introduced to postprocess the final design
- ☞ weight of 3 objectives to obtain a single objective





MOGA RSM Blending



The final optimisation is run on a blend of:



75% RSM virtual



25% MOGA real experiments



MOGA setting



4 generations of 20 experiments



RSM blend



10 generations of 20 experiments



50 real



150 virtual



is re-trained and updated each generation



Total CPU time is reduced of 50%

20 SOBOL X 4 MOGA



RSM GA initial training



10 MOGA generations of 20 experiments:
5 real
15 virtual

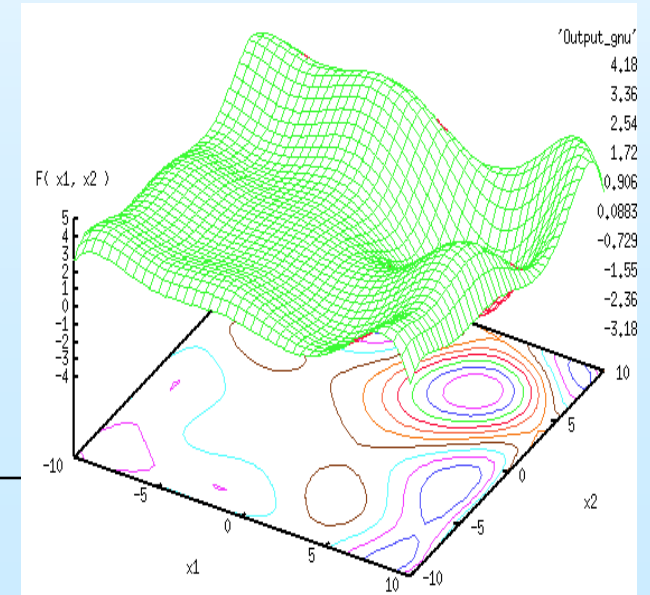
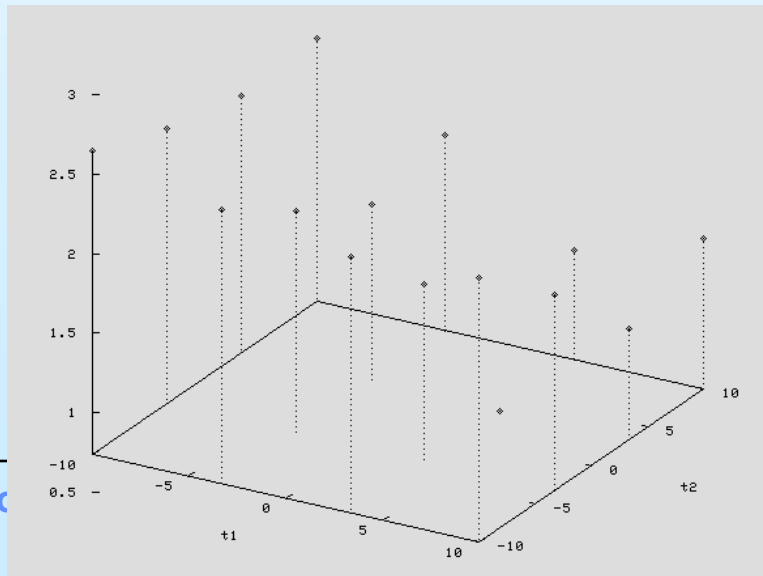
RSM training each generation on the 5 additional real experiments





RSM

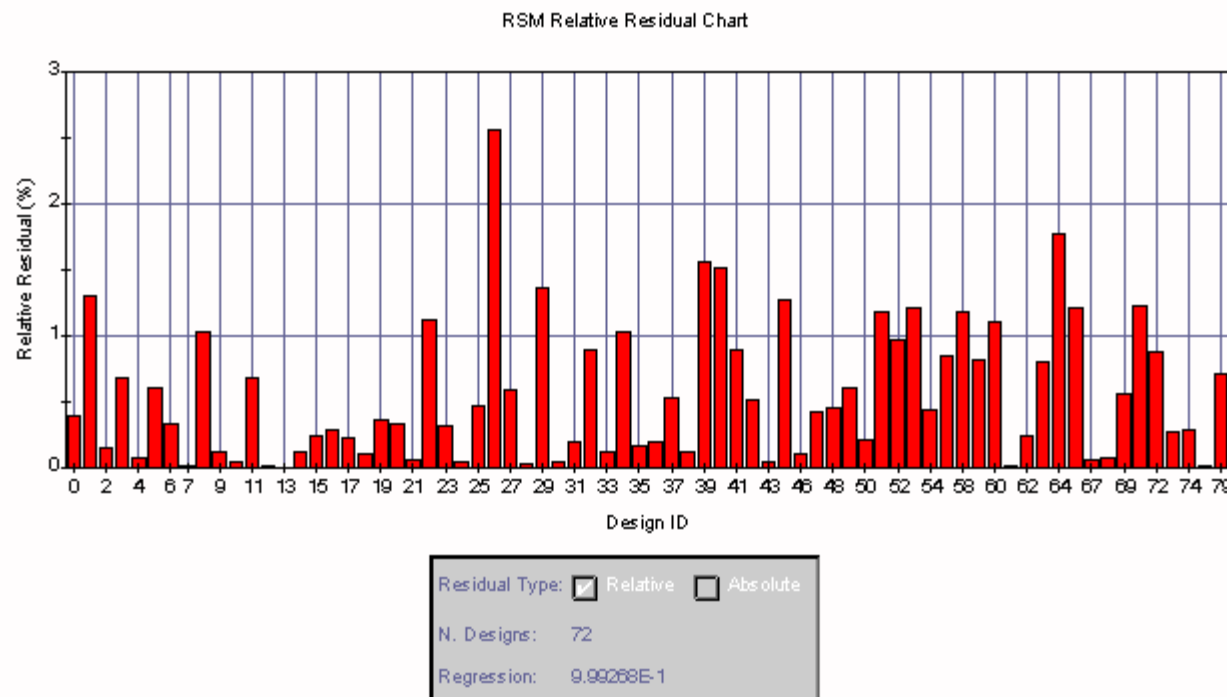
- ☞ On the 80 experiments SOBOL-MOGA, a response surface is fitted so that experiments can be performed virtually on the N -dimensions response surface instead of going through an explicit CFD run
- ☞ Basically an experiment on a RSM has CPU time of less than 1 sec while the average CFD run takes 90 minutes:
 - 📄 Advantage: ENORMOUS CPU TIME SAVING
 - 📄 Disadvantage: Response Surface must have low errors and virtual results (if **chosen**) must be validated by CFD



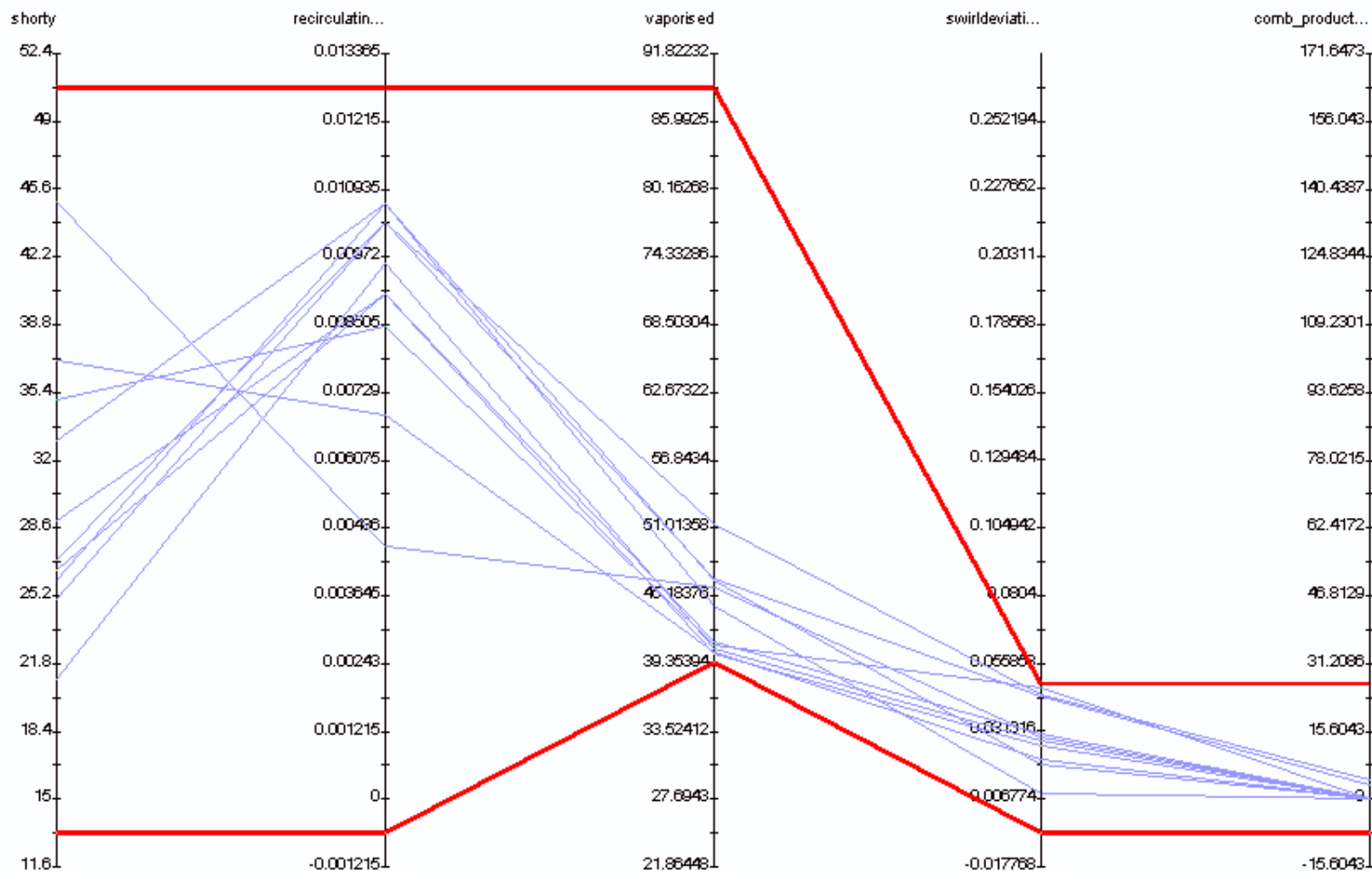


RSM

- 🖱 a fitting is performed by gaussian interpolation
- 🖱 the errors are checked on all real experiments
- 🖱 sample surface on %fuel vaporised at 4th generation

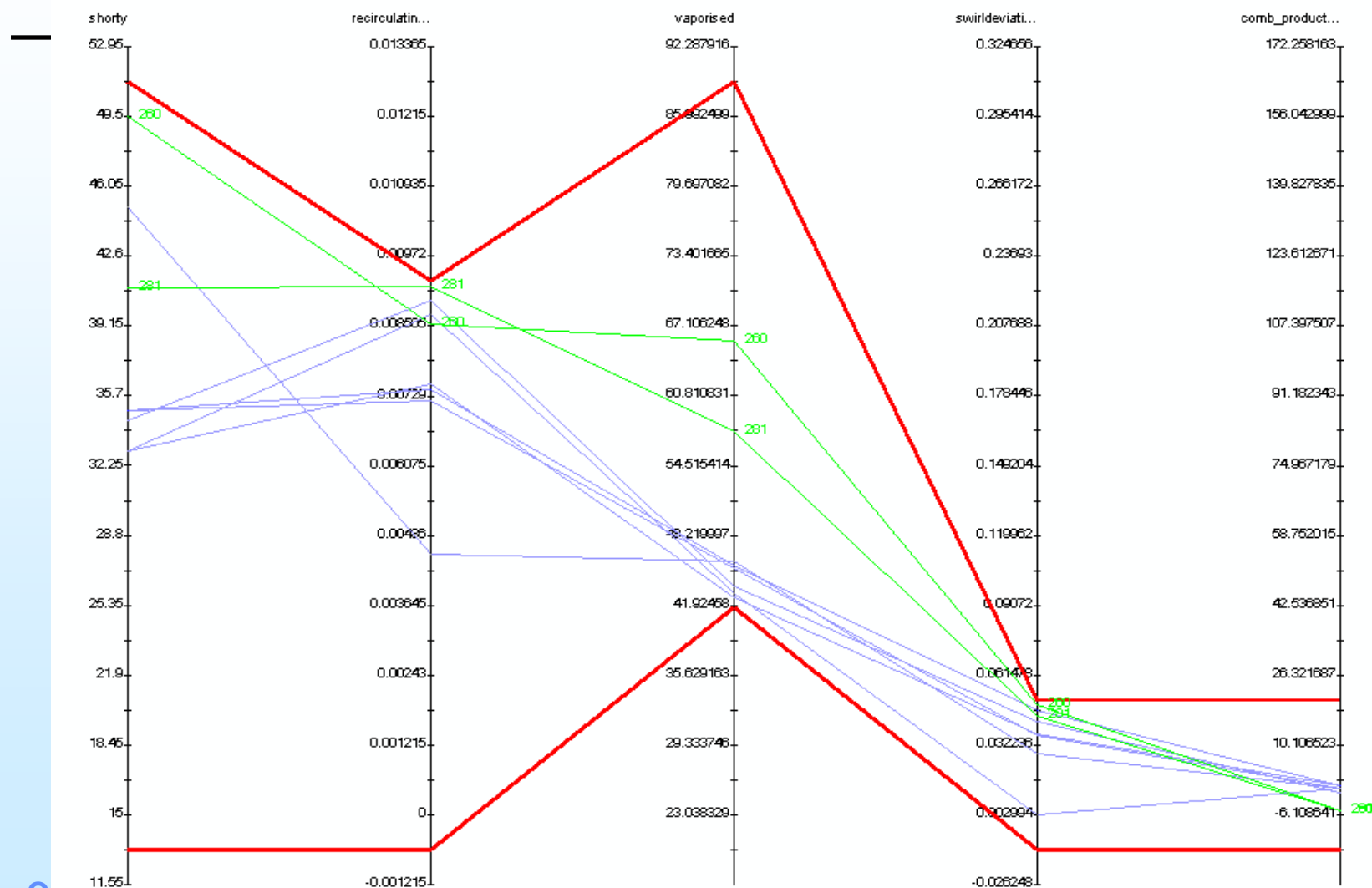


Parallel Chart Convergence



Shift + Drag Mouse to Zoom. Press 'r' to reset. Click on line to mark.

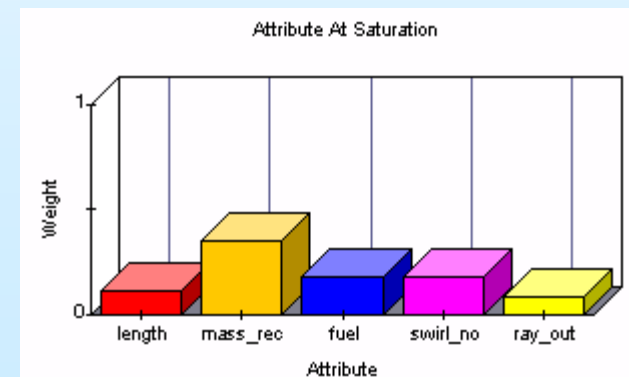
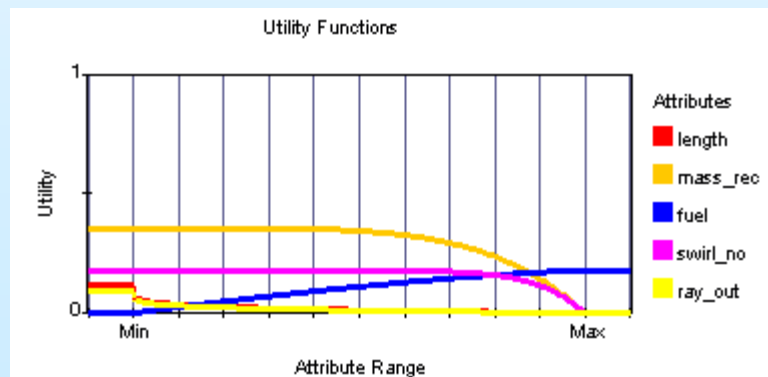
Parallel chart postprocessing



Weights are introduced for each output variable

Marked	First Attribute	Type	Weight	Second Attribute
<input checked="" type="checkbox"/>	swirl_no	greater than	2.0	ray_out
<input checked="" type="checkbox"/>	fuel	greater than	1.5	length
<input checked="" type="checkbox"/>	swirl_no	equal to	1.0	fuel
<input checked="" type="checkbox"/>	mass_rec	greater than	3.0	length

Non linear weighing functions are computed

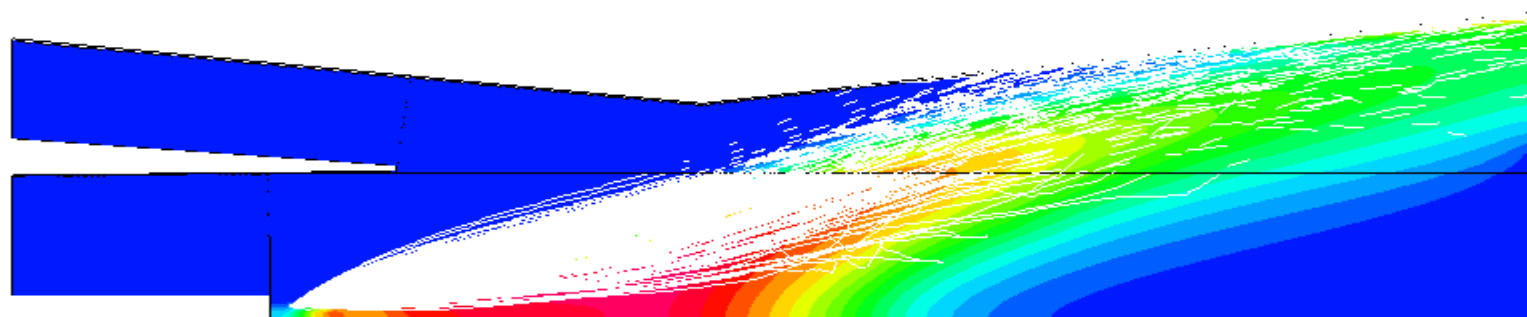


Design ranking

Design No.	length	mass_rec	fuel	swirl_no	ray_out	Rank Value
45	45.0	0.0	75.59436	0.2180011	0.00907218	0.696718006342...
18	49.0	0.9883296	72.13689	0.0544705	0.0106934	0.693395846394...
2	40.0	73.97912	72.97001	0.0462573	0.00996328	0.690309713192...
5	15.0	34.89241	39.2496	0.2459233	0.0106934	0.686747862539...
29	15.0	25.74149	39.1771	0.2476789	0.0103283	0.685246411073...
68	45.0	1.36824	67.624	0.0851953	0.0110585	0.684698460919...
260	49.5	-5.083780795681...	65.730085808563...	0.0488729864080...	0.0085448456882...	0.681538510871...
64	45.0	0.0	64.13435	0.109817	0.00961084	0.678128166238...

 **Design 260 is virtual on RSM : if chosen must be validated**

Design	Length	% Fuel Vap.	Δ Swirl NO.	Recirculation	Rec. Radii
1 Real	30.00	41.10%	0.077	0.00	0.096
260 Virtual	49.50	65.71%	0.048	-5.08	0.085
260 Real	49.50	69.72%	0.047	0.00	0.09



MASS_FRACTION1

6.000E-02

5.700E-02

5.400E-02

5.100E-02

4.800E-02

4.500E-02

4.200E-02

3.900E-02

3.600E-02

3.300E-02

3.000E-02

2.700E-02

2.400E-02

2.100E-02

1.800E-02

1.500E-02

1.200E-02










9.000E-03

6.000E-03

3.000E-03

0.000E+00



- 
3 Objectives have been simultaneously chased
 -  minimising recirculating radii
 -  minimising length
 -  maximising % vaporised fuel
- 
Two main goals are obtained
 -  Flashback is avoided (constraint of recirculation combustor products)
 -  Desired swirl number is obtained
 -  It means that a tuning of 2 mass flow rates and 2 swirl angles can make the same vaporiser yield different swirl numbers for different combustor can requirements
 -  It has been tested with success on two similar vaporisers chasing different swirl numbers